

# Computational Approaches to Mixed Integer Second Order Cone Optimization (MISOCP)

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INFORMS Annual Meeting 2017,  
23 October 2017

- 1 Algorithms for MISOCP
- 2 DisCO Solver
- 3 Computational Experiments
- 4 Conclusion

# MISOCP Definition

- We are interested in solving Mixed Integer Second Order Conic Optimization (MISOCP) problems.
- MISOCP is a generalization of Mixed Integer Linear Optimization (MILP).
- MISOCP can be formulated as follows,

$$\begin{aligned} \min \quad & c^\top x \\ \text{s.t.} \quad & Ax = b \\ & x \in \mathbb{L}^1 \times \cdots \times \mathbb{L}^k \\ & x_i \in \mathbb{R}_+ \quad \quad \quad i \in I \\ & x_j \in \mathbb{Z}_+ \quad \quad \quad j \in J. \end{aligned} \tag{MISOCP}$$

# Motivation: Evaluation of Solution Approaches for MISOCP

- Choice of branch and bound subproblem: LP vs SOCP?
- What does an LP-based branch and cut for MISOCP look like?
- How to balance cutting and branching for LP-based approach?
- Do MILP cuts help in case of LP-based subproblems?
- Do disjunctive conic cuts help?
- Which branching strategy to use?

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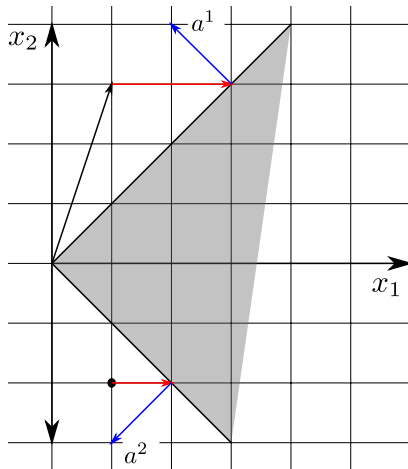


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# Separating Infeasible Directions/Solutions

Figure: Separation Example



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  - 2: Relax all integrality and conic constraints to create root node LP.
  - 3: **while** there are nodes to process **do**
  - 4:     Pick a node.
  - 5:     Solve LP, if LP solution is feasible, update bounds and go to line 3.
  - 6:     Decide whether to constrain or branch.
  - 7:     **while** cutting is preferred **do**
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# Whether to Cut or Branch

Let  $\bar{x}$  be LP subproblem solution.

- If  $\bar{x}$  is conic infeasible,
  - Generate Outer Approximation (OA) cuts for at least  $\alpha$  iterations.
  - Generate OA cuts for at most  $\gamma$  iterations if  $\bar{x}$  is integer infeasible too.
  - After  $\alpha$  iterations, generate OA cuts if last improvement in the LP bound was greater than  $\beta$  times difference of LP bound to current upper bound.
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- Uses *conic* OSI to manipulate SOCP subproblems.
- Default behavior is LP-based branch and cut using CLP and *conic* CGL.
- Cplex, Mosek and Ipopt can be used through *conic* OSI interface.
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# Experimental Details

- Problem set contains CBLIB2014 problems, 6 Steiner Tree Problems and 41 randomly generated problems.
- Experiments are conducted in COR@L Lab, each node has 16 processors at 2 GHz and 32 GB of memory.
- Memory allowed for serial runs is limited to 2GB.
- Memory limit for parallel runs is 2GB per process.
- Time limit is 7100 seconds.
- Cplex 12.7 is used to solve SOCP problems.

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Table: SOCP-based Branch and Bound Variations Experimented

Parameters	referred as
default	disco-socp
strong branching	disco-socp-strong
disjunctive cuts in root	disco-socp-dc-all
only best disjunctive cut	disco-socp-dc-best
parallel bb-socp with OpenMPI	disco-socp-mpi

**Table:** OA Branch and Cut Variations Experimented

Parameters	referred as
$\alpha \leftarrow 1, \beta \leftarrow 0.001, \gamma \leftarrow 50$	disco-lp
strong branching	disco-lp-strong
$\alpha \leftarrow 2$	disco-lp-2
$\alpha \leftarrow 4$	disco-lp-3
$\beta \leftarrow 0.01$	disco-lp-4
$\beta \leftarrow 0.0001$	disco-lp-5
$\gamma \leftarrow 20$	disco-lp-6
$\gamma \leftarrow 100$	disco-lp-7
add all disjunctive cuts at root node	disco-lp-dc-all
add only best disjunctive cut at root node	disco-lp-dc-best
no MILP cuts	disco-lp-nomilpcuts
parallel version with OpenMPI	disco-lp-mpi

Figure: disco-socp, CPU Time, Branching Strategies

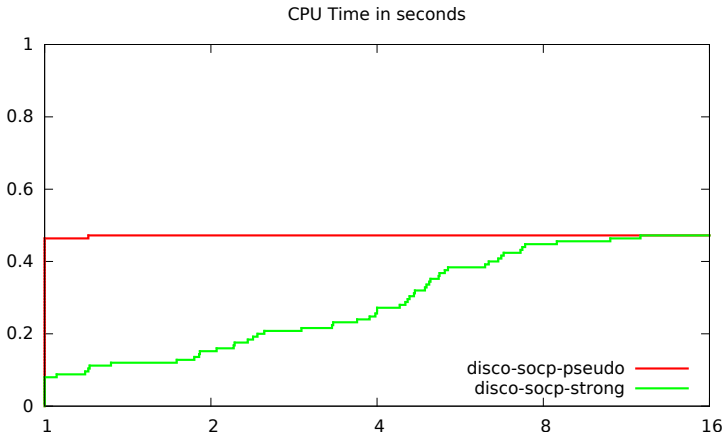


Figure: disco-socp, Number of Nodes, Branching Strategies

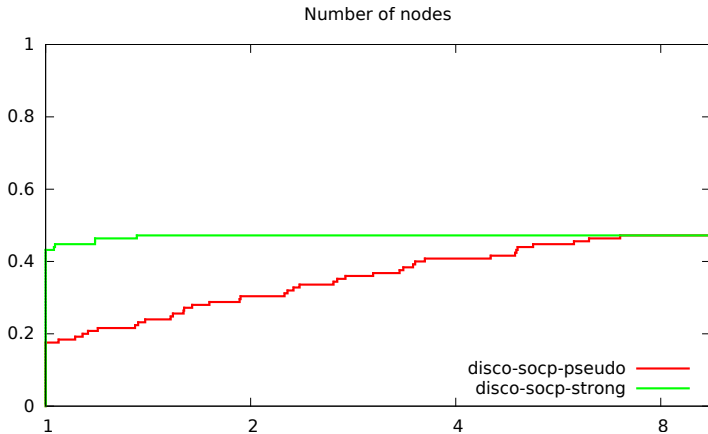


Figure: disco-lp, CPU Time, Branching Strategies

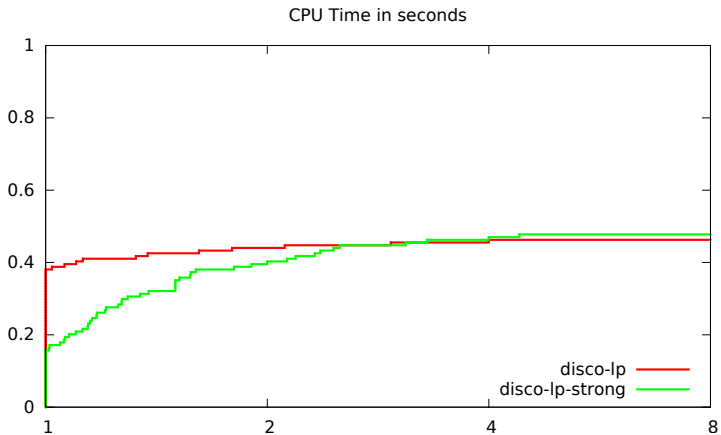


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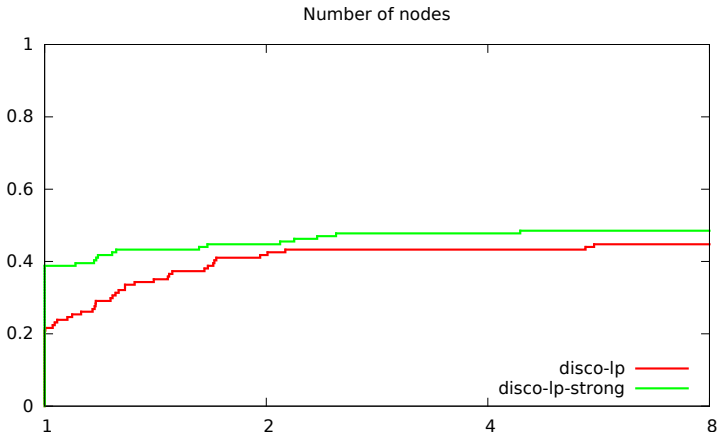




Figure: disco-lp, CPU Time, OA Cut Parameters

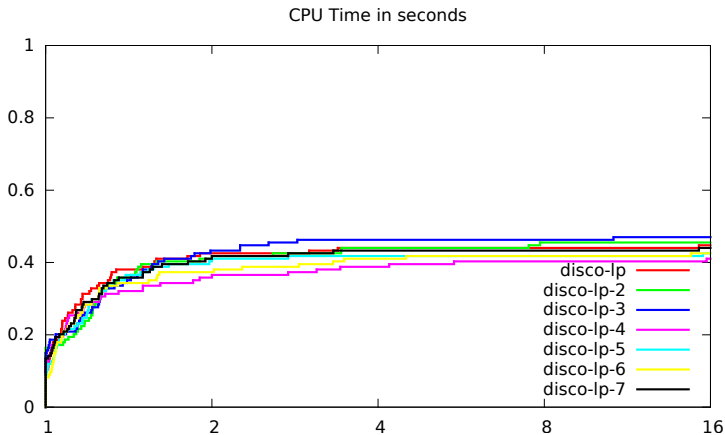


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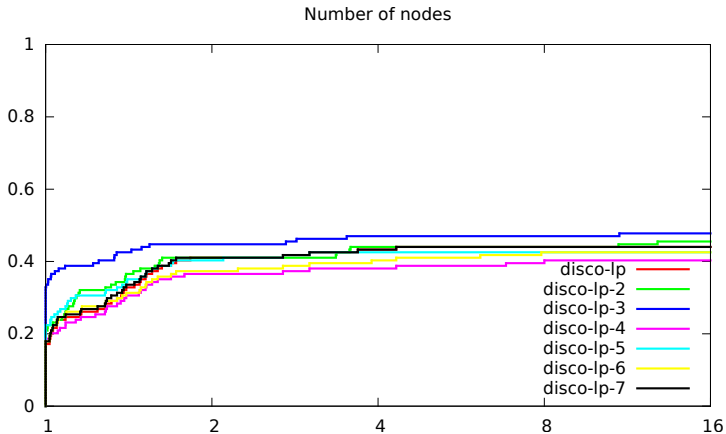


Figure: disco-lp, CPU Time without MILP Cuts

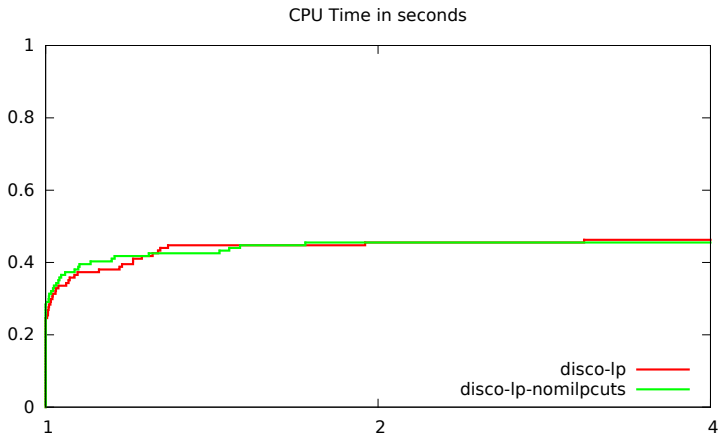


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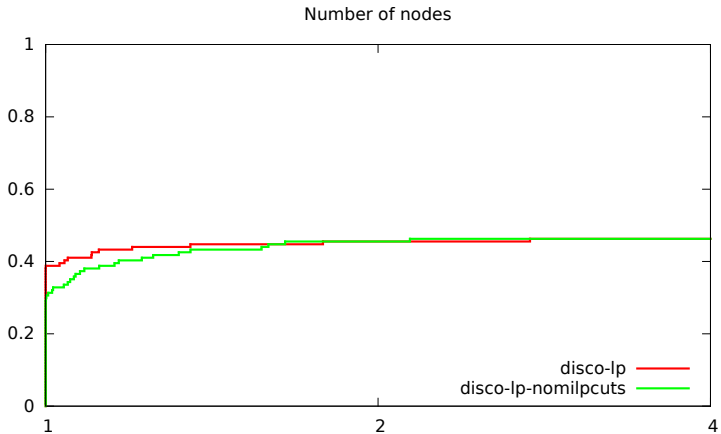


Figure: disco-socp, CPU Time with Disjunctive Cuts

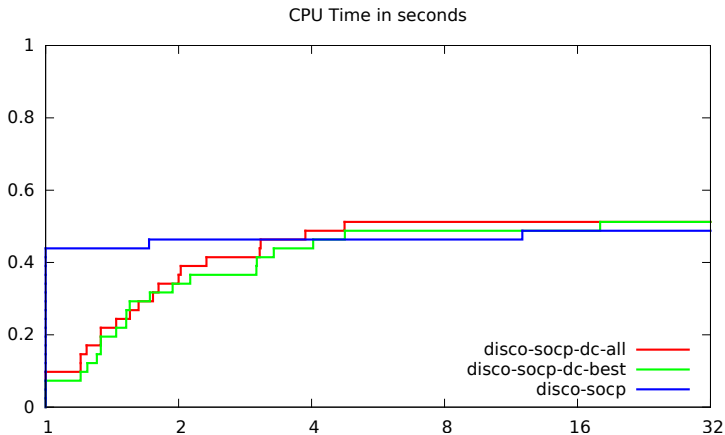


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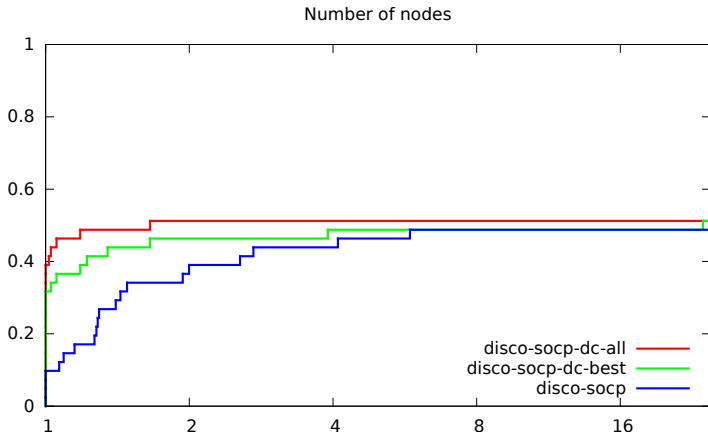


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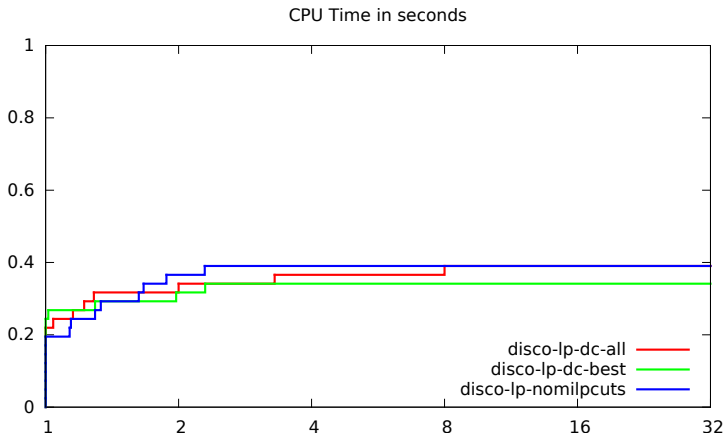


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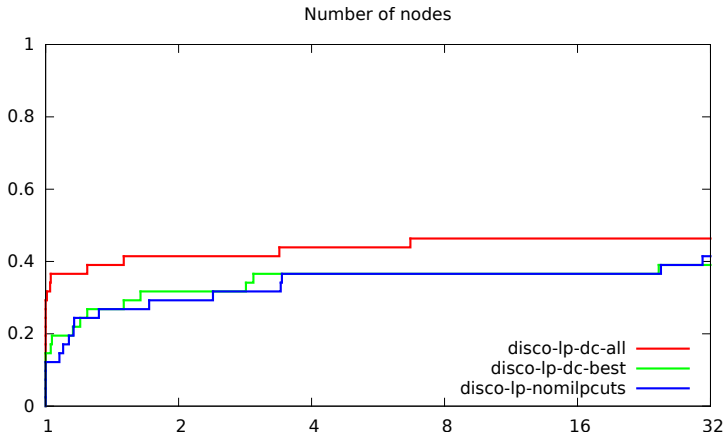




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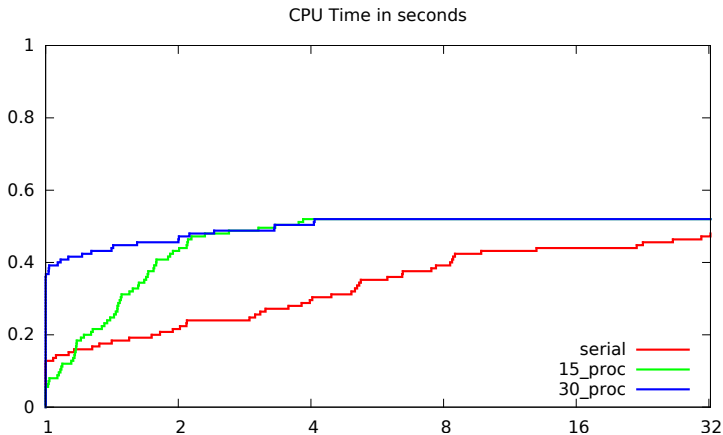


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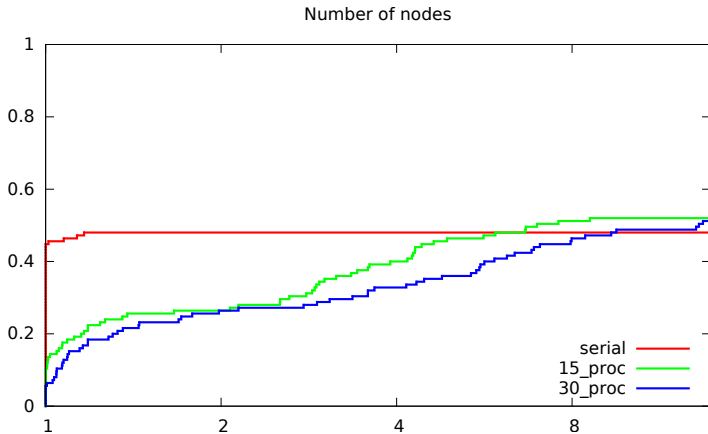


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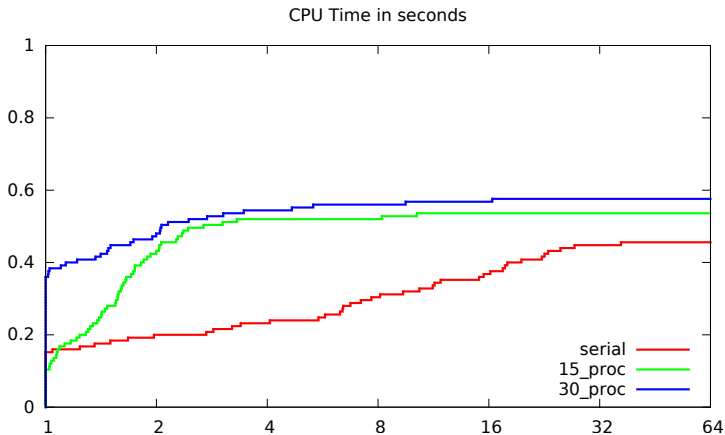


Figure: disco-lp, Number of Nodes Processed, Parallel Runs

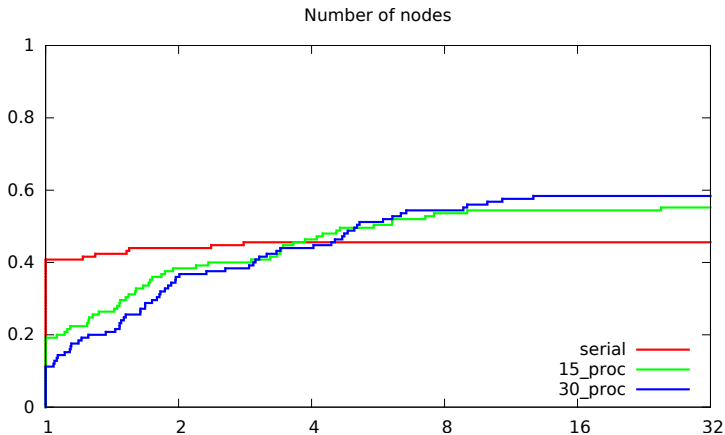


Figure: disco-lp versus disco-socp, CPU Time

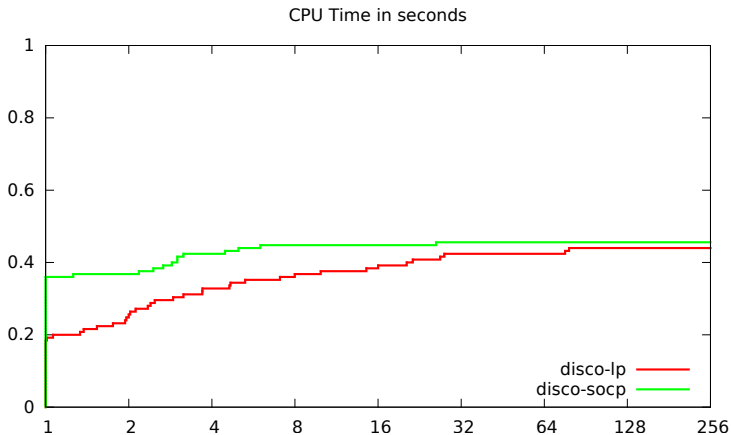


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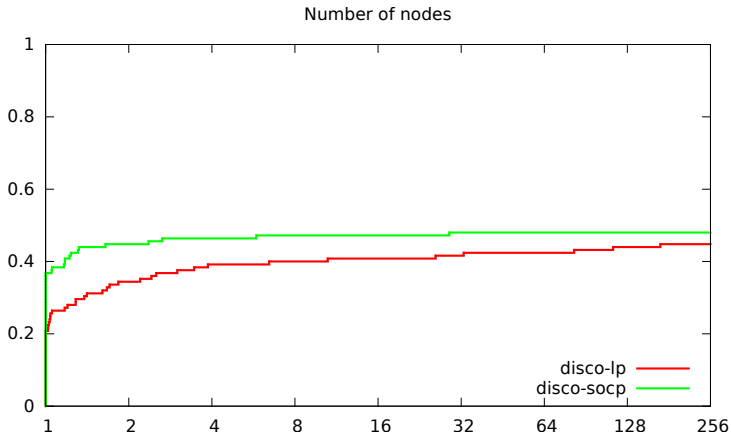


Figure: disco-lp versus disco-socp, Problems with Low Dimensional Cones

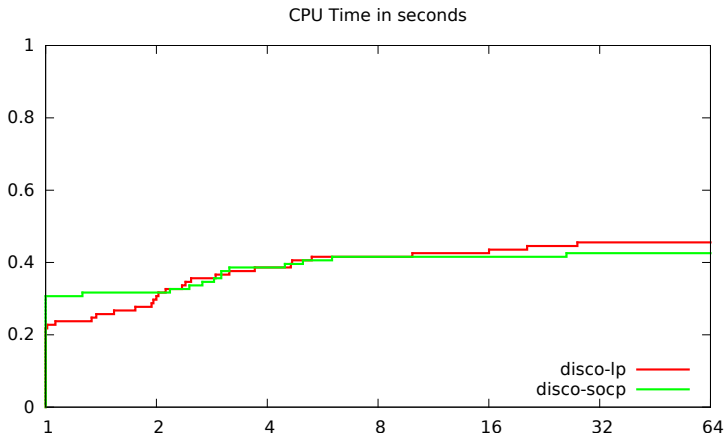


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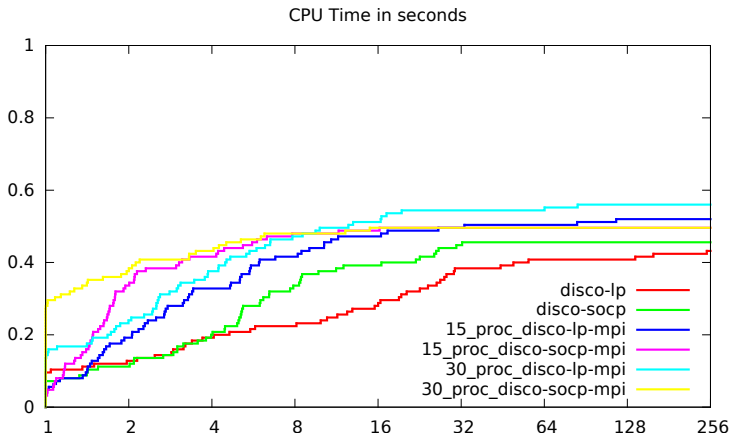
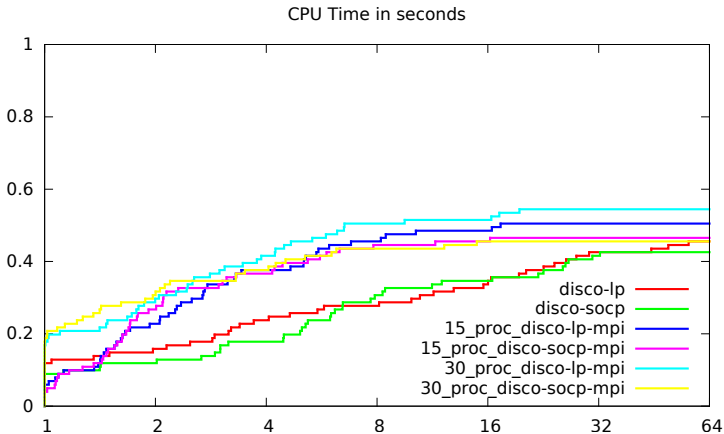




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# Conclusion

- Use SOCP-based subproblems for instances with large cones.
- LP-based subproblems might perform better for instances with low dimensional cones.
- Use LP-based subproblems for instances that are difficult and have large branch and bound trees.
- Strong branching might help with LP-based subproblems on hard instances.
- Right cut parameters are crucial in case of LP-based subproblems.
- Disjunctive cuts might help depending on the instance. They might perform better with LP-based subproblems.
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- Disjunctive cuts might help depending on the instance. They might perform better with LP-based subproblems.
- MILP cuts does not help much.

# Conclusion

- Use SOCP-based subproblems for instances with large cones.
- LP-based subproblems might perform better for instances with low dimensional cones.
- Use LP-based subproblems for instances that are difficult and have large branch and bound trees.
- Strong branching might help with LP-based subproblems on hard instances.
- Right cut parameters are crucial in case of LP-based subproblems.
- Disjunctive cuts might help depending on the instance. They might perform better with LP-based subproblems.
- MILP cuts does not help much.



# Clone, Try, Contribute

`https://github.com/aykutbulut`

`https://github.com/coin-or`

# References