

IE 495 Lecture 2

August 31, 2000

Reading for this lecture

- Primary
 - Miller and Boxer, Chapter 5
 - Aho, Hopcroft, and Ullman, Chapter 1
 - Fountain, Chapter 4
- Secondary
 - Roosta, Chapter 2
 - Cosnard and Trystram, Chapters 4

Interconnection Networks

Aside: Introduction to Graphs

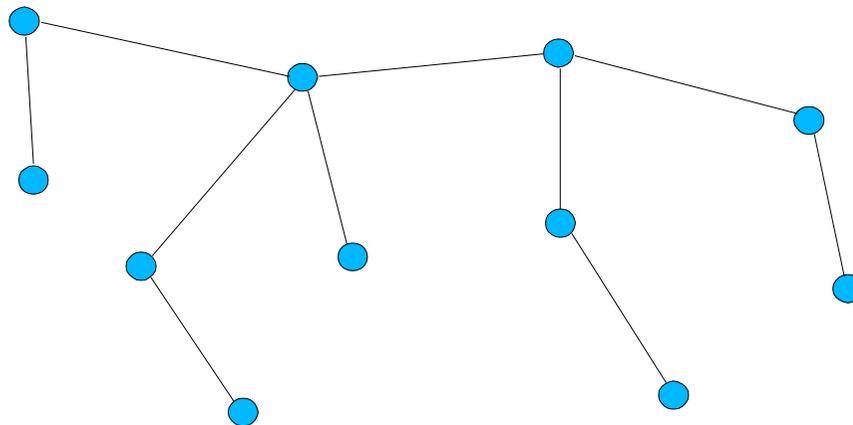
- A graph $G = (V, E)$ is defined by two sets, a finite, nonempty set V of *vertices* (or nodes) and a set $E \subseteq V \times V$ of *edges*.
- Example: A road network.
- The edges can be either ordered pairs or unordered pairs.
- If the edges are ordered pairs, then they are usually called *arcs* and the graph is called a *directed graph*.
- Otherwise, the graph is called *undirected*.
- See AHU, Section 2.3

(Undirected) Graph Terms

- Vertices u and v are *endpoints* of the edge (u, v) .
- We say an edge $e = (u, v)$ is *incident to* its endpoints.
- Two vertices u and v are *adjacent* if $(u, v) \in E$.
- The *degree* of a vertex is the number of edges incident to it (equivalently, the number of vertices adjacent to it).
- A *path* is a sequence of edges $(v_1, v_2), (v_2, v_3), \dots, (v_{n-1}, v_n)$
- The *length* of such a path is $n-1$.
- Often, we represent a path simply as a sequence of vertices.

Applications of Graph Theory

- Graph theory is a very rich subject area
- Sample Applications
 - Shortest Path Problem
 - Minimum Spanning Tree
 - Traveling Salesman Problem



What is an interconnection network?

- A graph (directed or undirected)
 - The nodes are the processors
 - The edges represent direct connections
- Properties and Terms
 - Degree of the Network
 - Communication Diameter
 - Bisection Width
 - Processor Neighborhood
 - Connectivity Matrix
 - Adjacency Matrix

Measures of Goodness

- **Communication diameter:** The maximum shortest path between two processors.
- **Bisection width:** The minimum cut such that the two resulting sets of processors have the same order of magnitude.
- Connectivity Matrix
- Adjacency Matrix

Connectivity Matrices

Example 1

	0	1	2	3
0		■		■
1	■		■	
2		■		■
3	■		■	

Connectivity Matrices

Example 2

	0	1	2	3
0		■		
1	■		■	
2		■		■
3			■	

2-step Connectivity Matrices

Example 2

	0	1	2	3
0		■	■	
1	■		■	■
2	■	■		■
3		■	■	

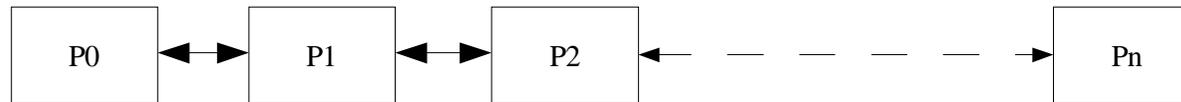
N-step Connectivity Matrices

- Indicates the processor pairs that can reach each other in N steps
- Computed using Boolean matrix multiplication
- The corresponding **adjacency matrix** indicates how many disjoint paths connect each pair.

	0	1	2	3
0	1	1	1	
1	1	1	1	1
2	1	1	1	1
3		1	1	1

	0	1	2	3
0	1	1	2	1
1	1	1	1	2
2	2	1	1	1
3	1	2	1	1

Linear Array

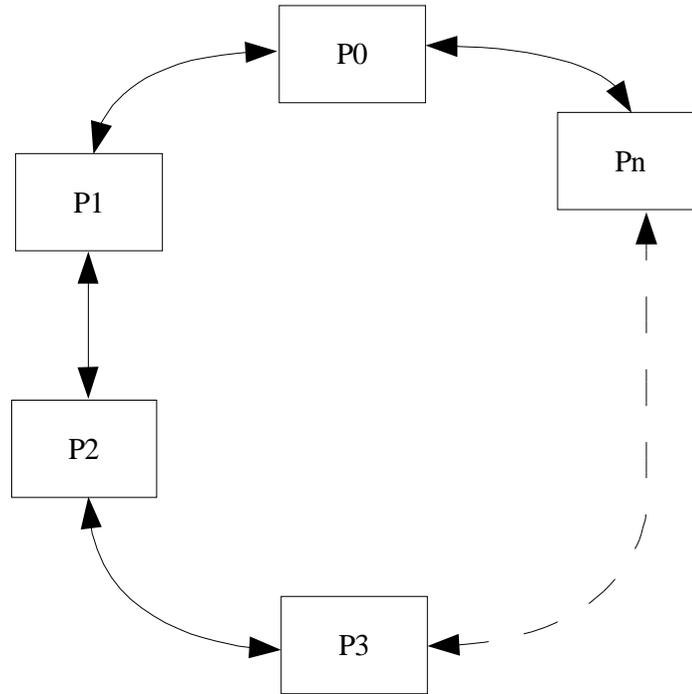


Diameter

Bisection Width

Degree

Ring



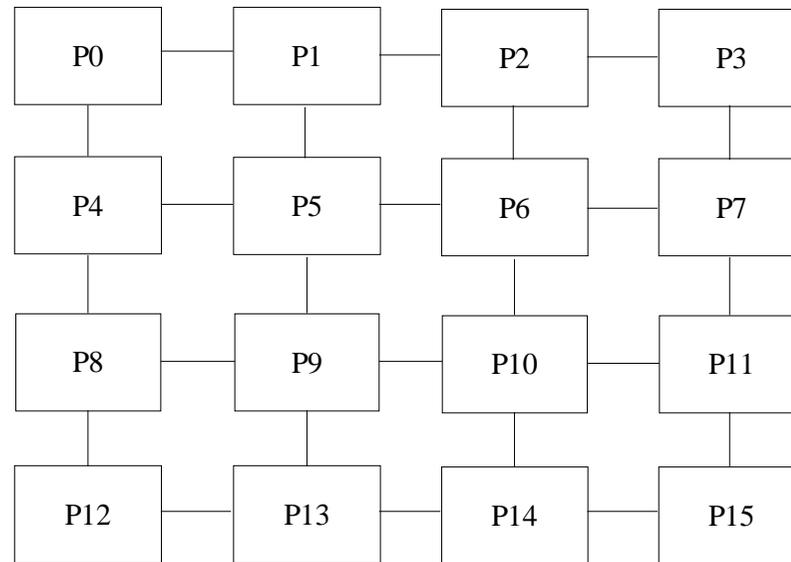
Diameter



Bisection Width

Degree

Mesh



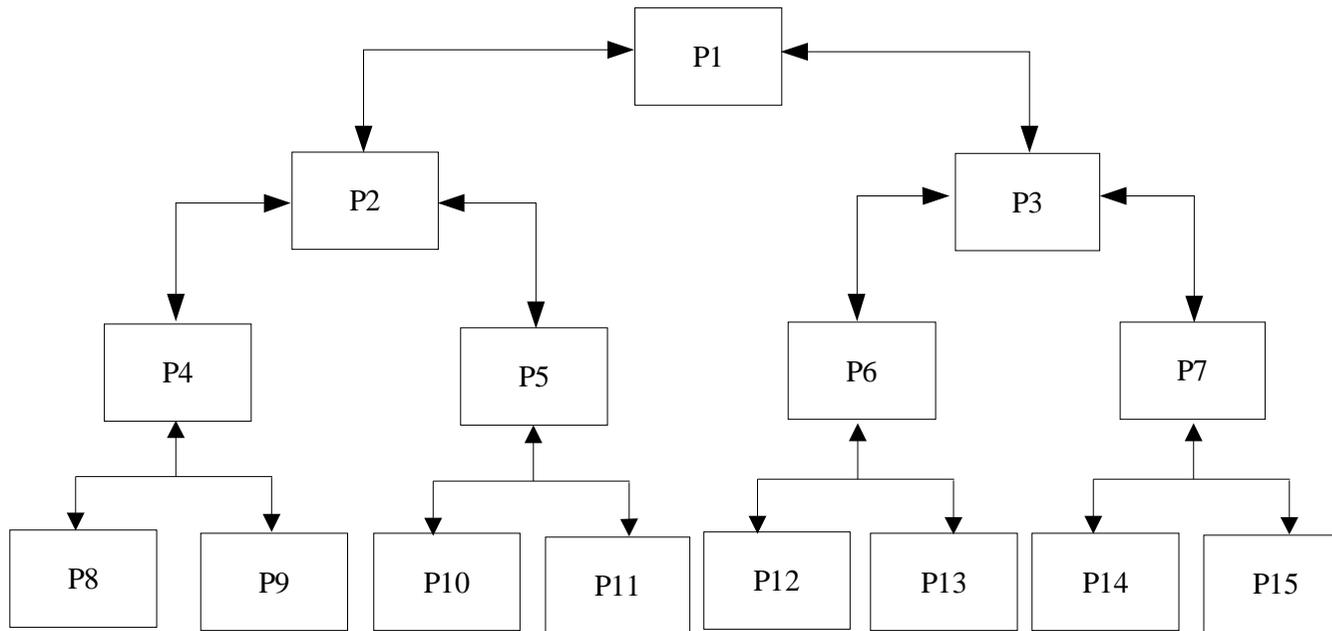
Diameter



Bisection Width

Degree

Tree



Diameter



Bisection Width

Degree

Other Schemes

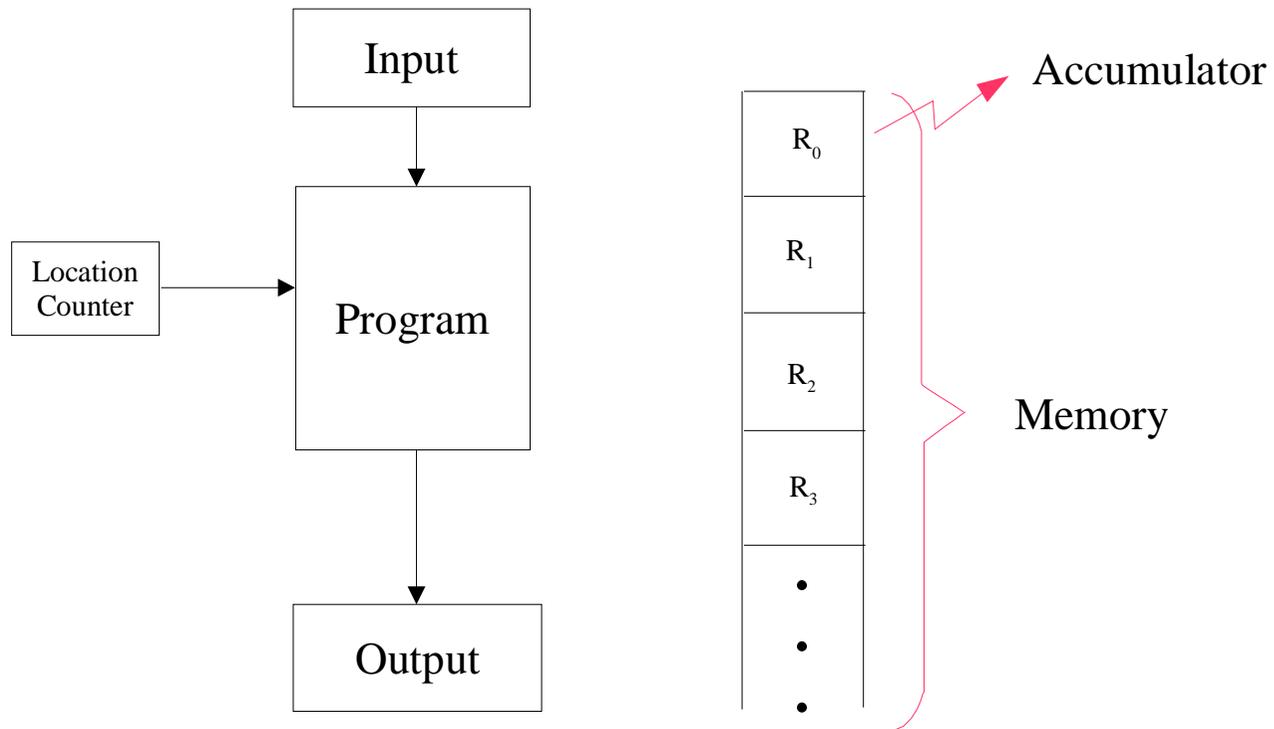
- **Pyramid:** A 4-ary tree where each level is connected as a mesh
- **Hypercube:** Two processors are connected if and only if their ID #'s differ in exactly one bit.
 - Low communications diameter
 - High bisection width
 - Doesn't have constant degree
- **Perfect Shuffle:** Processor i is connected *one-way* to processor $2i \bmod (N-1)$.
- **Others:** Star, De Bruijn, Delta, Omega, Butterfly

Models of Computation

Analysis of Algorithms

- We are interested in the **time** and **space** needed to perform an algorithm.
- There are several ways of approaching this analysis.
 - Worst case
 - Average case
 - Best case
- Worst case is the most common type of analysis (why?).
- Generally speaking, time is the most constraining resource.

Random Access Machine Model



A RAM Program

- At each time step, one elementary operation is completed.
- Sample list of elementary operations

- LOAD

- STORE

- ADD

- SUB

- MULT

- DIV

- READ

- WRITE

- JUMP

- JGTZ

- JZERO

- HALT