

Financial Optimization

ISE 347/447

Lecture 12

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Reading for This Lecture

- C&T Chapter 8

Parameter Estimation in Portfolio Optimization

- To use Markovitz portfolio optimization in practice, one has to estimate the parameters μ_i and Q_{ij} ($i = 1, \dots, n$) from historical data.
- For recent previous investment periods $[t_{k-1}, t_k]$ ($k = 1, \dots, T$) having the same length as the current investment period, we can compute the returns

$$r_k^i = \frac{S_{t_k}^i - S_{t_{k-1}}^i}{S_{t_{k-1}}^i}.$$

- These numbers can be seen as independent samples of the distribution of R_i .

Method 1: Sample returns and covariances

- A simple approach is to estimate μ_i as the sample average return of asset i over the T previous investment periods,

$$\hat{\mu}_i = \frac{1}{T} \sum_{k=1}^T r_k^i.$$

- The covariance Q_{ij} can be estimated similarly as

$$\hat{Q}_{ij} = \frac{1}{T-1} \sum_{k=1}^T (r_k^i - \hat{\mu}_i)(r_k^j - \hat{\mu}_j).$$

Method 2: Capital Asset Pricing Model (CAPM)

- A far better method for estimating μ and σ from historical data is to use a market index S^m as a benchmark.

- Samples

$$r_k^m = \frac{S_{t_k}^m - S_{t_{k-1}}^m}{S_{t_{k-1}}^m}$$

of the random market return R^m are computed the same way as for other assets.

- Likewise, the risk-free returns r_k^f over the same periods can be obtained.

The CAPM Model

The aim is to find a model

$$r_k^i = r_k^f + \beta_i(r_k^m - r_k^f) + \varepsilon_k^i$$

that explains the excess return of the i^{th} asset over the risk-free return as a sum of two parts:

- $\beta_i(r_k^m - r_k^f)$ is fully explained by asset i 's correlation with the market,
- ε_k^i is independent of the market and due to an unknown level of *idiosyncratic risk* σ_i^2 associated with asset i .
 - We interpret ε_k^i ($k = 1, \dots, T$) as i.i.d. samples of a Gaussian random variable $\mathcal{E}^i \sim \mathcal{N}(0, \sigma_i^2)$.
 - This part of the return is also thought of as being independent between different assets.

Fitting the Model

- We choose the model that minimizes the sample estimate of the idiosyncratic risk,

$$\sigma_i^2 = \min_{\beta_i} \frac{1}{T-1} \sum_{k=1}^n (r_k^i - r_k^f - \beta_i(r_k^m - r_k^f))^2,$$

$$\beta_i = \arg \min_{\beta_i} \frac{1}{T-1} \sum_{k=1}^n (r_k^i - r_k^f - \beta_i(r_k^m - r_k^f))^2.$$

- Taking derivatives with respect to β_i , it is easy to check that

$$\beta_i = \frac{\sum_k (r_k^i - r_k^f)(r_k^m - r_k^f)}{\sum_k (r_k^m - r_k^f)^2}.$$

- Under the CAPM model, one then stipulates

$$R_i = r_f + \beta_i(R_m - r_f) + \mathcal{E}^i.$$

The Estimators

- Therefore,

$$\mu_i = r_f + \beta_i(\mathbb{E}[R^m] - r_f),$$

$$\begin{aligned} Q_{ij} &= \text{Cov}(r_f + \beta_i(R^m - r_f) + \mathcal{E}^i, r_f + \beta_j(R^m - r_f) + \mathcal{E}^j) \\ &= \beta_i\beta_j\sigma^2(R^m) + \delta_{ij}\sigma_i\sigma_j, \end{aligned}$$

where δ_{ij} is the Kronecker delta.

- Replacing $\mathbb{E}[R^m]$ and $\sigma^2(R^m)$ by their sample estimators

$$\hat{\mu}_m = T^{-1} \sum_k r_k^m,$$

$$\hat{\sigma}_m^2 = \frac{1}{T-1} \sum_k (r_k^m - \hat{\mu}_m)^2,$$

we obtain the estimators

$$\hat{\mu}_i = r_f + \beta_i(\hat{\mu}_m - r_f),$$

$$\hat{Q}_{ij} = \beta_i\beta_j\hat{\sigma}_m^2 + \delta_{ij}\sigma_i\sigma_j.$$

The Multifactor CAPM Model

- The CAPM model can be generalized by replacing the benchmark index S^m with multiple indices S^{m_1}, \dots, S^{m_q} for which samples

$$r_k^{m_j} = \frac{S_{t_k}^{m_j} - S_{t_{k-1}}^{m_j}}{S_{t_{k-1}}^{m_j}}$$

are available.

- The aim is now to find the best-fitting linear model

$$r_k^i = r_k^f + \sum_{j=1}^q \beta_i^j (r_k^{m_j} - r_k^f) + \varepsilon_k^i,$$

in full analogy to the above model.

Fitting the Multifactor Model

- We again choose the model that minimizes the sample estimate of the idiosyncratic risk,

$$\sigma_i^2 = \min_{(\beta_i^1, \dots, \beta_i^q)} \frac{1}{T-1} \sum_{k=1}^n \left(r_k^i - r_k^f - \sum_{j=1}^q \beta_i^j (r_k^{m_j} - r_k^f) \right)^2,$$

$$(\beta_i^1, \dots, \beta_i^q) = \arg \min_{(\beta_i^1, \dots, \beta_i^q)} \frac{1}{T-1} \sum_{k=1}^n \left(r_k^i - r_k^f - \sum_{j=1}^q \beta_i^j (r_k^{m_j} - r_k^f) \right)^2.$$

- This is a strictly convex quadratic optimization problem when $T \geq q$, so the optimizer $(\beta_i^1, \dots, \beta_i^q)$ can be computed by solving the linear system

$$\nabla_{(\beta_i^1, \dots, \beta_i^q)} \sum_{k=1}^n \left(r_k^i - r_k^f - \sum_{j=1}^q \beta_i^j (r_k^{m_j} - r_k^f) \right)^2 = 0. \quad (1)$$

The Estimators

- Let $B = (\beta_i^j)$ be the matrix of coefficients obtained when solving (1) for $(i = 1, \dots, n)$.
- The multifactor CAPM model stipulates that

$$R = r_f e + B(P - r_f e) + \mathcal{E},$$

where $P = [P_1 \dots P_q]^\top$ is the unknown random vector of returns

$$P_j = \frac{S_1^{m_j} - S_0^{m_j}}{S_0^{m_j}}$$

of the chosen indices over the investment period $[0, 1]$.

The Estimators (cont.)

- Therefore,

$$\mu = r_f e + B(\mathbb{E}[P] - r_f e),$$

$$Q = B \text{Cov}(P) B^\top + \text{Diag}(\sigma_1^2, \dots, \sigma_n^2),$$

where $\text{Cov}(P)$ is the variance-covariance matrix of P .

- Replacing $\mathbb{E}[P]$ and $\text{Cov}(P)$ by their sample estimates yields the CAPM estimators for μ and Q .

The Black-Litterman Model

- This is really a method for estimating the vector μ of expected returns.
- The resulting estimates can be used in conjunction with any portfolio optimization model.
- As before, we assume an investment universe consists of n risky assets S^1, \dots, S^n and one risk-free asset S^0 with returns R^1, \dots, R^n (random) and r_f (deterministic) respectively over the investment period $[0, 1]$.
- We write $\tilde{R} = \begin{bmatrix} r_f \\ R \end{bmatrix}$, $\tilde{\mu} = \begin{bmatrix} r_f \\ \mu \end{bmatrix}$ and

$$\tilde{Q} = \text{Cov}(\tilde{R}) = \begin{pmatrix} 0 & 0 \\ 0 & Q \end{pmatrix},$$

where $Q = \text{Cov}(R)$.

Key Assumptions

1. All investors use the investment strategy that maximizes

$$(M) \max_{\tilde{x} \in \mathbb{R}^{n+1}} \tilde{\pi}^\top \tilde{x} - \lambda \tilde{x}^\top \tilde{Q} \tilde{x}$$
$$\text{s.t.} \quad \sum_{i=0}^n \tilde{x}_i = 1,$$

where $\tilde{\pi} = \begin{bmatrix} r_f \\ \pi \end{bmatrix}$ is an unknown vector of expected returns.

2. λ and Q are known (in reality this means they have already been estimated via some method of choice).
3. μ is itself modelled as a random vector $\mu = \pi + \nu$, where π is a return vector implied by the market and $\nu \sim N(0, \tau Q)$ for some small τ

Key Assumptions (cont.)

The motivation for Assumption 3 is that if $R \sim \mathcal{N}(\mu, Q)$ and R^1, \dots, R^T are T independent samples of R , then the sample mean

$$\hat{\mu} = \frac{1}{T} \sum_{i=1}^T R^i$$

has distribution $\mathcal{N}(\mu, T^{-1}Q)$.

Features of the Model

- The key distinguishing feature of the model is to allow investors to *specify their beliefs* about the performance of certain portfolios.
- This information is taken into account by updating the a priori estimate π of μ in a Bayes-like fashion to obtain an improved estimator.
- A key concept is the *return implied by the market*.
- Let \tilde{w} be the relative weights of the assets in the market capitalization, i.e.,

$$\tilde{w}_i = \frac{z_i S^i}{\sum_{i=0}^n z_i S^i},$$

where z_i is the number of shares of asset i that exist in the market and S^i the value of each share.

The Return Implied by the Market

- If Assumption 1 holds, \tilde{w} must be the maximizer of (M).
- Otherwise the market would not be at equilibrium and prices would quickly adjust.
- Mathematically, this implies that \tilde{w} has to satisfy the KKT conditions of (M),

$$\tilde{\pi} - 2\lambda\tilde{Q}\tilde{w} - \eta e^{[n+1]} = 0 \quad (2)$$

$$\sum_{i=0}^n \tilde{w}_i = 1. \quad (3)$$

- Here η is an unknown Lagrange multiplier, and $e^{[n+1]}$ is the $n + 1$ -dimensional vector of ones.

The Return Implied by the Market (cont.)

- Recalling that by Assumption 2, λ and \tilde{Q} are known, we can solve for π .

- Since

$$\tilde{Q} = \text{Cov}(\tilde{R}) = \begin{pmatrix} 0 & 0 \\ 0 & Q \end{pmatrix},$$

the first line of (2) reads $\eta = r_f$.

- Therefore,

$$\pi = r_f e^{[n]} + 2\lambda Q w.$$

- Having computed π , we now know the a priori distribution of μ ,

$$\mu \sim \text{N}(\pi, \tau Q).$$

- This is the *return implied by the market*.

Beliefs About the Market

- Market equilibrium is never quite reached because investors process new information at different speeds.
- Fund managers who process information faster than others therefore want the expected returns to reflect their insight or beliefs about where the market is headed next.
- For example, a manager who believes that the return of asset i is expected to outperform that of asset j by 2% would want μ to satisfy the constraint

$$\mu_i - \mu_j = 0.02.$$

Modeling Market Beliefs

- More generally, the fund manager may have several such beliefs concerning the expected returns of certain portfolios constructed from the risky assets S^1, \dots, S^n , resulting in the constraints

$$A\mu = b,$$

where A is a $k \times n$ -matrix and b a k -dimensional vector.

- A natural way of incorporating such beliefs into the parameter estimation problem is to use the conditional expectation

$$\hat{\mu} = \mathbb{E}[\mu \mid A\mu = b]$$

as the estimator of the expected returns of assets S^1, \dots, S^n .

Conditioning on Beliefs

- The conditional density of μ given $A\mu = b$ is

$$f(\mu \mid A\mu = b) = \frac{\exp\{-\frac{1}{2}(\mu - \pi)^\top (\tau Q)^{-1}(\mu - \pi)\}}{\int_{\{x: Ax=b\}} \exp\{-\frac{1}{2}(x - \pi)^\top (\tau Q)^{-1}(x - \pi)\} dx}$$

- Thus, the conditional distribution $\mathcal{D}(\mu \mid A\mu = b)$ is a multivariate Gaussian centered at $\hat{\mu}$, which is where $f(\mu \mid A\mu = b)$ is maximized.
- Therefore, $\hat{\mu}$ is the minimizer of the convex QP

$$\begin{aligned} \text{(P)} \quad & \min_{\mu} (\mu - \pi)^\top (\tau Q)^{-1}(\mu - \pi) \\ & \text{s.t. } A\mu = b. \end{aligned}$$

The Estimators

- Thus, $\hat{\mu}$ is determined by the KKT conditions of problem (P):

$$(\tau Q)^{-1}(\hat{\mu} - \pi) = A^\top \eta \quad (4)$$

$$A\hat{\mu} = b, \quad (5)$$

where η is a vector of Lagrange multipliers.

- From (4) we get

$$\hat{\mu} = \pi + \tau Q A^\top \eta, \quad (6)$$

and from (5), $b = A\hat{\mu} = A\pi + \tau AQA^\top \eta$.

- Hence,

$$\eta = (\tau AQA^\top)^{-1}(b - A\pi)$$

and

$$\hat{\mu} = \pi + QA^\top (AQA^\top)^{-1}(b - A\pi). \quad (7)$$

Strength of Beliefs

- In reality, fund managers are never quite certain about their predictions.
- Therefore, we can also add randomness to the belief system $A\mu = b$ by expressing it as

$$A\mu = b + \mathcal{E}, \quad (8)$$

where $\mathcal{E} \sim \mathbf{N}(0, D)$ is a multivariate normal with zero mean and diagonal covariance matrix $D = \text{Diag}(\sigma_1^2, \dots, \sigma_n^2)$.

- In other words, the uncertainties pertaining to different constraints are considered to be independent.
- The larger the parameter σ_i^2 , the less certain the investor is about the belief encoded in the i^{th} row of the system (8).

Incorporating Uncertain Beliefs

- Beliefs of the form $A\mu = b + \mathcal{E}$ cannot be conditioned upon, as they do not express an event.
- With some messy algebra, we can show that the generalized posterior distribution of μ is

$$\mathcal{D}(\mu \mid A\mu = b + \mathcal{E}) = \text{N}(\hat{\mu}, [(\tau Q)^{-1} + A^\top D^{-1} A]^{-1}),$$

where

$$\hat{\mu} = [(\tau Q)^{-1} + A^\top D^{-1} A]^{-1} [(\tau Q)^{-1} \pi + A^\top D^{-1} b].$$

is the generalized posterior estimator of μ .

- Note that as uncertainty about the beliefs grows, $\hat{\mu}$ tends to the a priori estimator π ,

$$\lim_{D \rightarrow \infty} \hat{\mu} = [(\tau Q)^{-1}]^{-1} (\tau Q)^{-1} \pi = \pi,$$

as one would expect.