

Advanced Mathematical Programming

IE417

Lecture 5

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Reading for This Lecture

- Chapter 3, Sections 4-5
- Chapter 4, Section 1

Maxima and Minima of Convex Functions

Minimizing a Convex Function

Theorem 1. *Let S be a nonempty convex set on \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$ be convex on S . Suppose that x^* is a local optimal solution to $\min_{x \in S} f(x)$.*

- *Then x^* is a global optimal solution.*
- *If either x^* is a strict local optimum or f is strictly convex, then x^* is the unique global optimal solution.*

Necessary and Sufficient Conditions

Theorem 2. Let S be a nonempty convex set on \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$ be convex on S . The point $x^* \in S$ is an optimal solution to the problem $\min_{x \in S} f(x)$ if and only if f has a subgradient ξ such that $\xi^T(x - x^*) \geq 0 \quad \forall x \in S$.

- This implies that if S is open, then x^* is an optimal solution if and only if there is a zero subgradient of f at x^* .

Alternative Optima

Theorem 3. Let S be a nonempty convex set on \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$ be convex on S . If the point $x^* \in S$ is an optimal solution to the problem $\min_{x \in S} f(x)$, then the set of alternative optima are characterized by the set

$$S^* = \{x \in S : \nabla f(x^*)^T (x - x^*) \leq 0 \text{ and } \nabla f(x^*) = \nabla f(x)\}$$

Corollaries:

Maximizing a Convex Function

Theorem 4. Let S be a nonempty convex set on \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$ be convex on S . If the point $x^* \in S$ is an optimal solution to the problem $\max_{x \in S} f(x)$, then $\xi^T(x - x^*) \leq 0 \quad \forall x \in S$, where ξ is any subgradient of f .

Theorem 5. Let S be a nonempty compact polyhedral set on \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$ be convex on S . An optimal solution x^* to the problem $\max_{x \in S} f(x)$ exists where x^* is an extreme point of S .

Importance of Convexity

- Allows easy approximation.
- Allows easy global optimization.
- Allows easy constrained optimization over polyhedral sets.

Generalizing Convexity

Quasiconvex Functions

Definition 1. Let S be a nonempty convex set in \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$. The function f is said to be **quasiconvex** if, for each $x_1, x_2 \in S$, we have

$$f[\lambda x_1 + (1 - \lambda)x_2] \leq \max\{f(x_1), f(x_2)\}$$

Theorem 6. Let S be a nonempty convex set in \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$. The function f is quasiconvex if and only if $S_\alpha = \{x \in S : f(x) \leq \alpha\}$ is convex for each $\alpha \in \mathbb{R}$.

Strictly Quasiconvex Functions

Definition 2. Let S be a nonempty convex set in \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$. The function f is said to be **strictly quasiconvex** if, for each $x_1, x_2 \in S$ with $f(x_1) \neq f(x_2)$, we have

$$f[\lambda x_1 + (1 - \lambda)x_2] < \max\{f(x_1), f(x_2)\}$$

Theorem 7. Let S be a nonempty convex set in \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$ be strictly quasiconvex. Consider the problem of minimizing f over S . If \hat{x} is a local optimal solution, then \hat{x} is a global optimal solution.

- Note that strict quasiconvexity does not imply quasiconvexity unless the function is lower semicontinuous.

Strongly Quasiconvex Functions

Definition 3. Let S be a nonempty convex set in \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$. The function f is said to be **strictly quasiconvex** if, for each $x_1, x_2 \in S$ with $x_1 \neq x_2$, we have

$$f[\lambda x_1 + (1 - \lambda)x_2] < \max\{f(x_1), f(x_2)\}$$

Theorem 8. Let S be a nonempty convex set in \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$ be strictly quasiconvex. Consider the problem of minimizing f over S . If \hat{x} is a local optimal solution, then \hat{x} is the unique global optimal solution.

Pseudoconvex Functions

Definition 4. Let S be a nonempty convex set on \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$ be differentiable on S . The function f is said to be **pseudoconvex** if $\forall x_1, x_2 \in S$, with $\nabla f(x_1)^T(x_2 - x_1) \geq 0$, we have $f(x_2) \geq f(x_1)$.

- *Strictly pseudoconvex* can be defined analogously.
- *Notice that all convex functions are pseudoconvex.*
- Also, for a pseudoconvex function f , if $\nabla f(x^*) = 0$, then x^* is a local minimum.

Local Convexity

Definition 5. Let S be a nonempty convex set on \mathbb{R}^n and let $f : S \rightarrow \mathbb{R}$. Then the following are local properties of f .

- f is said to be convex at x^* if $f(\lambda x^* + (1 - \lambda)x) \leq \lambda f(x^*) + (1 - \lambda)f(x)$ for each $\lambda \in (0, 1)$ and $x \in S$.
- f is said to be pseudoconvex at x^* if $\nabla f(x^*)^T(x - x^*) \geq 0$ implies $f(x) \geq f(x^*)$.