Graphs and Network Flows
IE411

Lecture 11

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References for Today's Lecture

- Required reading
  - Sections 21.3
- References
  - AMO Chapter 5
  - CLRS Chapter 25

Label-Correcting Algorithms

- Generic
  - $O(n^2C)$ iterations (recall $d(j)$ bounded by nC and $-nC$)
  - No specified method for selecting an arc violating optimality conditions
- Modified
  - By repeatedly scanning arcs in a fixed order, we can get a strongly polynomial time algorithm.
  - Practical improvement: Maintain a list of arcs that *might* violate optimality conditions
    - If we decrease $d(j)$, what do we know about reduced lengths of incoming arcs? outgoing arcs?
    - Which arcs could violate optimality conditions after a label is modified?

Special Implementations of Modified Label-Correcting

- FIFO Label-Correcting
  - $O(mn)$ is best strongly polynomial-time implementation
  - Maintain a queue and examine nodes in FIFO order
- Dequeue Implementation
  - a *dequeue* allows elements to be added or deleted from both front and back
  - always select nodes from front; add previously seen nodes to front, all others to back
  - $O(nmC)$ but performs well in practice for sparse networks

FIFO Label-Correcting Algorithm

Input: A network $G = (N, A)$ and a vector of arc lengths $c \in \mathbb{Z}^A$

Output: $d(i)$ is the length of a shortest path from node s to node i and pred(i) is the immediate predecessor of i in an associated shortest paths tree.

$d(s) \leftarrow 0$ and $pred(s) \leftarrow 0$
$d(j) \leftarrow \infty$ for each $j \in N \setminus \{s\}$
$Q \leftarrow \{s\}$
while $Q \neq \emptyset$ **do**
  Remove the first element i from Q
  for $(i, j) \in A(i)$ **do**
    if $d(j) > d(i) + c_{ij}$ **then**
      $d(j) \leftarrow d(i) + c_{ij}$
      $pred(j) \leftarrow i$
      if $j \notin Q$ **then**
        add j to the end of Q
      end if
    end if
  end for
end while

All-Pairs Shortest Path Problem

- Determine the shortest path distance between every pair of nodes in the network.
  - Assume underlying network is *strongly connected*
  - Assume network does not contain a negative cost cycle
- Algorithms
  - Repeated Shortest Path
  - All-Pairs Label-Correcting

Repeated Shortest Path Algorithm (Non-Negative Arc Lengths)

- For each node $i \in N$, solve a single-source shortest path problem with node i as the source using any appropriate algorithm.
- Complexity: Let $S(n, m, C)$ denote the time required to solve a shortest path problem with non-negative arc lengths. Then, the complexity is $O(n \cdot S(n, m, C))$.

Repeated Shortest Path Algorithm (Negative Arc Lengths)

- Transform the network into one with non-negative arc lengths.
- For each node $i \in N$, solve a single-source shortest path problem with node i as the source using any appropriate algorithm.
- Compute the shortest path distances in the original network from the shortest path distances in the transformed network.
- Complexity: $O(nm + n \cdot S(n, m, C)) = O(n \cdot S(n, m, C))$.

Shortest Path Optimality Conditions

Theorem 1. *For every pair of nodes $[i, j] \in N \times N$, let $d[i, j]$ represent the length of some directed path from node i to node j satisfying $d[i, i] = 0 \ \forall i \in N$ and $d[i, j] \leq c_{ij} \ \forall (i, j) \in A$. These distances represent* shortest path distances *if and only if they satisfy*

$$d[i, j] \leq d[i, k] + d[k, j] \ \forall i, j, k \in N.$$

PROOF:

$\Rightarrow$ If these distances represent shortest path distances, they satisfy $d[i, j] \leq d[i, k] + d[k, j] \ \forall i, j, k \in N$.

$\Leftarrow$ If a set of distance labels satisfy $d[i, j] \leq d[i, k] + d[k, j] \ \forall i, j, k \in N$, then they represent shortest path distances.

All-Pairs Label-Correcting Algorithm

Input: A network $G = (N, A)$ and a vector of arc lengths $c \in \mathbb{Z}^A$

Output: $d[i, j]$ is the length of a shortest path from node i to node j for pairs i and j.

$d[i, j] \leftarrow \infty$ for all $[i, j] \in N \times N$

$d[i, j] \leftarrow 0$ for all $i \in N$

for $(i, j) \in A$ **do**

  $d[i, j] \leftarrow c_{ij}$

end for

while $\exists (i, j, k)$ satisfying $d[i, j] > d[i, k] + d[k, j]$ **do**

  $d[i, j] := d[i, k] + d[k, j]$

end while

Floyd-Warshall Algorithm

- $O(n^3C)$ iteration complexity of algorithm is not appealing(!)
- Given matrix of distances $d[i,j]$, we need to perform n^3 comparisons just to test optimality
- Floyd-Warshall cleverly obtains matrix of shortest path distances within $O(n^3)$ computations

Floyd-Warshall Algorithm

Input: A network $G = (N, A)$ and a vector of arc lengths $c \in \mathbb{Z}^A$

Output: $d[i, j]$ is the length of a shortest path from node i to node j for pairs i and j.

for $(i, j) \in N \times N$ **do**
  $d[i, j] \leftarrow \infty$ and $pred[i, j] \leftarrow 0$
end for
for $i \in N$ **do**
  $d[i, i] \leftarrow 0$
end for
for $(i, j) \in A$ **do**
  $d[i, j] \leftarrow c_{ij}$ and $pred[i, j] := i$
end for
for $k = 1$ to n **do**
  for $[i, j] \in N \times N$ **do**
    if $d[i, j] > d[i, k] + d[k, j]$ **then**
      $d[i, j] \leftarrow d[i, k] + d[k, j]$
      $pred[i, j] \leftarrow pred[k, j]$
    end if
  end for
end for

Proof of Correctness

Claim 1. *After iteration k, $d[i,j]$ is the shortest path distance from node i to node j subject to the condition that the path uses only nodes $1, 2, \cdots, k$ as internal nodes.*

PROOF: (by induction)

Floyd-Warshall Algorithm

- Complexity?

Detecting Negative Cost Cycles

- Network contains negative cost cycle if
  - $d[i,i] < 0$ for some $i \in N$
  - $d[i,j] < -nC$ for some $[i,j] \in N \times N$
- For F-W, simply check $d[i,i] < 0$ when updating $d[i,i]$.
- How else could we check?