

Graphs and Network Flows

IE411

Lecture 20

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Network Simplex Algorithm

Input: A network $G = (N, A)$, a vector of capacities $u \in \mathbb{Z}^A$, a vector of costs $c \in \mathbb{Z}^A$, and a vector of supplies $b \in \mathbb{Z}^N$

Output: x represents a minimum cost network flow

Determine an initial feasible tree structure (T, L, U)

Let x be flow and π be node potentials associated with (T, L, U)

while Some non-tree arc violates the optimality conditions **do**

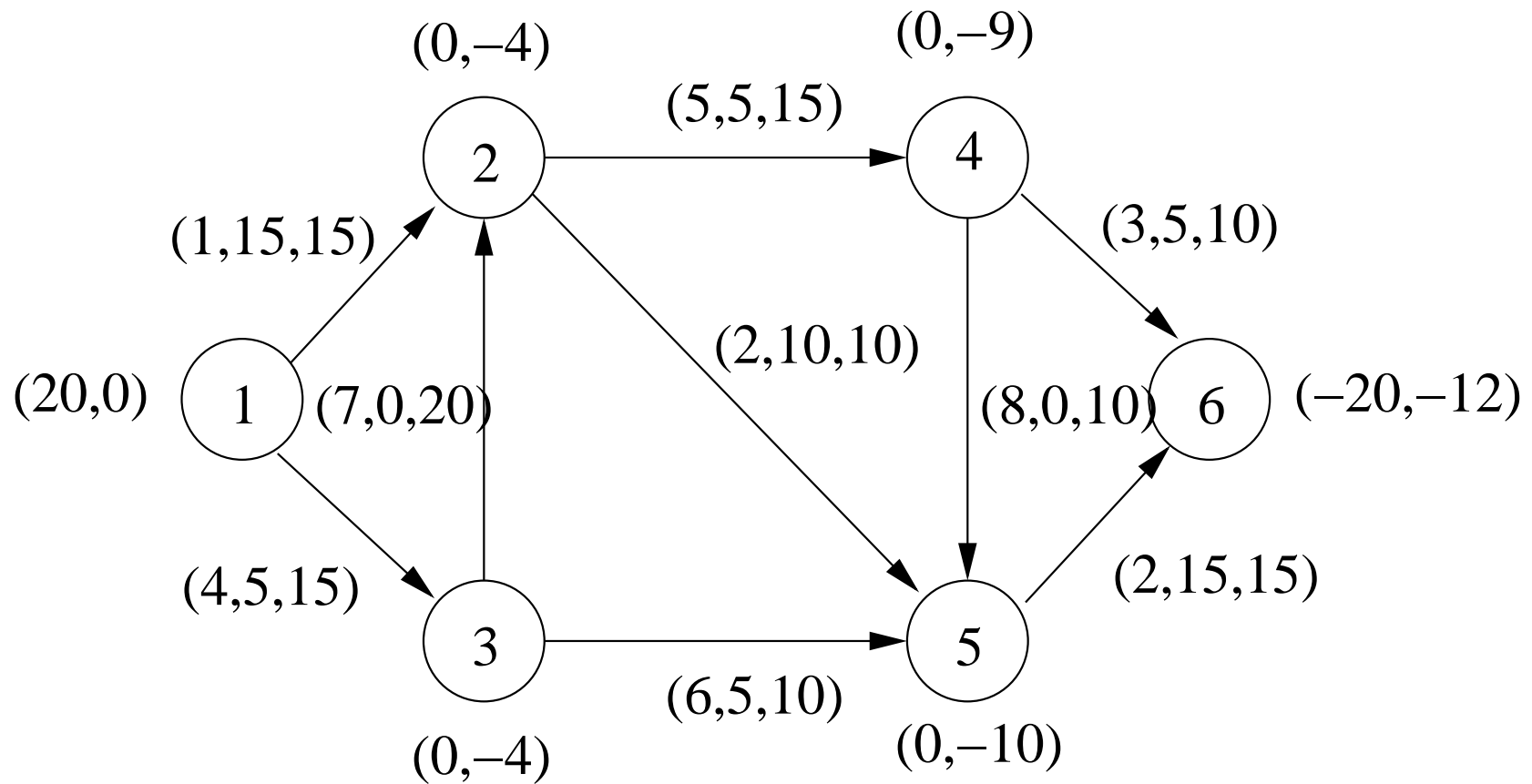
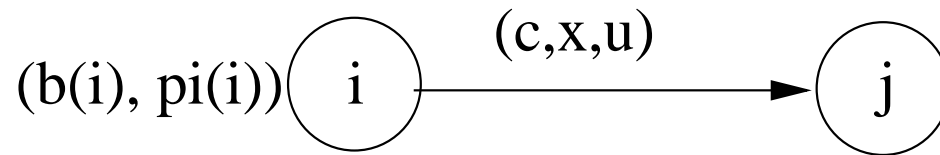
 Select an entering arc (k, l) violating optimality conditions

 Add arc (k, l) to tree and determine leaving arc (p, q)

 Perform a tree update and update solutions x and π

end while

Example



Degeneracy in Network Simplex

- Network simplex does not necessarily terminate in a finite number of iterations
- Poor choices of entering and leaving arcs lead to *cycling*
- Maintaining a *strongly feasible spanning tree* guarantees finite termination and speeds up the running time
- A pivot iteration is *non-degenerate* if $\delta > 0$ and is *degenerate* if $\delta = 0$
- A degenerate iteration occurs only if T is a degenerate spanning tree.
- If two arcs tie while determining the value of δ , the next spanning tree will be degenerate.

Strongly Feasible Spanning Trees

Let (T, L, U) be a spanning tree structure for a MCFP with integral data.

A spanning tree T is *strongly feasible* if

- every tree arc with zero flow is upward pointing (toward root) and every tree arc with flow equal to capacity is downward pointing (away from root)
- we can send a positive amount of flow from any node to the root along the tree path without violating any flow bound.

These two definitions are equivalent. Proof?

Modifications to Network Simplex Algorithm

- Initial Strongly Feasible Spanning Tree
 - Does our construction algorithm work?
 - * A non-degenerate spanning tree is always strongly feasible.
 - * A degenerate spanning tree is sometimes strongly feasible.
- Leaving Arc Rule
 - Select the leaving arc as the last blocking arc encountered in traversing the pivot cycle W along its orientation starting at the apex w .
 - Proof: Show that next spanning tree is strongly feasible.

Termination

- Each non-degenerate pivot strictly decreases objective function, so number of non-degenerate pivots is finite.
- To show: The pivot rule maintains the invariant that each spanning tree solution is strongly feasible.
 - Consider W_2 , the part of the cycle from p to apex: no arc can be blocking by pivot rule.
 - Consider W_1 , the part of the cycle from apex to q :
 - * If pivot is non-degenerate, then must be able to send flow backwards to root.
 - * If pivot is degenerate, then (p, q) must be contained in the part of the cycle from apex to k . Since the previous tree was strongly feasible and flows don't change, we must still be able to send positive flow back along W_1 .
- Note that each degenerate pivot must decrease the sum of the node potentials, so the number of degenerate pivots in between each successive non-degenerate pivot must also be finite.

Sensitivity Analysis

- Determine changes in optimal solution resulting from changes in data
 - arc cost
 - supply/demand
 - arc capacity
- Assuming spanning tree structure remains unchanged, if change in data affects
 - optimality → perform primal pivots to achieve optimality
 - feasibility → perform dual pivots to achieve feasibility

Cost Sensitivity Analysis

Suppose the cost of arc (p, q) increases by λ units.

Case 1 (p, q) is a non-tree arc

Case 2 (p, q) is a tree arc

Supply/Demand Sensitivity

- Suppose supply/demand $b(k)$ of node k increases by λ units. Then, the supply/demand $b(l)$ of some node l decreases by λ units.
- From the mass balance constraints, we know that we must ship λ units of flow from node k to node l .
- Let P be the unique tree path from node k to node l . And let $\delta = \min\{\delta_{ij} : (i, j) \in P\}$.
- If $\lambda \leq \delta$, then ...
- If $\lambda > \delta$, then ...

Capacity Sensitivity Analysis

- Suppose capacity of (p, q) increases by λ units.
- What do we know about previous optimal solution?
- If (p, q) is a tree arc or a non-tree arc at its lower bound
- If (p, q) is a non-tree arc at its upper bound