Advanced Operations Research Techniques IE316

Lecture 16

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Reading for This Lecture

- Bertsimas 6.1-6.3

Large-scale Linear Programming

- Linear programs occuring in practice can be extremely large.
- For large LPs, the vast majority of the matrix is superfluous.
- To solve a particular instance, we only need
  - Constraints that are binding at optimality.
  - Variables that are basic at optimality.
- In fact, we really only need constraints that have positive dual values and variables that have positive values at optimality.
- If we only had these variables and constraints from the start, we could solve very easily.
- The problem is that we don't know which variables and constraints these are.

Delayed Column Generation

- In problems with large numbers of variables, there are two main difficulties.
  - The time required just to *generate* the matrix.
  - The time required to calculate the reduced costs each iteration.
- We can address both of these problem with *delayed column generation*.
- Idea
  - Start with a subset of "promising" columns.
  - Solve the LP with just these columns.
  - *Price* the remaining columns and add those with negative reduced costs.
  - Iterate.

Automatic Delayed Column Generation

- In fact, we only need to find the column with the *most negative reduced cost*.
- *This is an optimization problem!*
- If we can solve this optimization problem, then we can solve the LP without explicitly listing the columns.
- There are many variants of this basic algorithm.
- All are based in the ability to *generate a column* with negative reduced cost, given the current dual prices.

Generic Column Generation Algorithm

- We are interested in solving an LP with a large number of columns.
- Consider the *restricted problem* obtained by considering only the subset of the columns indexed by set I.

$$\begin{aligned} min \sum_{i \in I} c_i x_i \\ s.t. \sum_{i \in I} A_i x_i = b \\ x \geq 0 \end{aligned}$$

- Solve this LP and calculate the optimal dual solution.
- Now, we must generate a new column A_j for which $c_j - c_B B^{-1} A_j < 0$.
- This can be done by solving the *column generation subproblem*

$$\min_{a \in C} c_a - c_B B^{-1} a,$$

where C is the global set of columns.

- If the minimum is < 0, add the new column to the set I and re-solve.

Maintaining the Restricted Problem

- Many variants of this algorithm can be obtained by changing how the set I is maintained.
- One obvious variant is to simply maintain every column that has been generated so far in I.
- Another variant is to throw away all the nonbasic columns after each iteration.
- There are many intermediate options.

Example: The Cutting Stock Problem

- A prototypical problem that can be solved by column generation is the *cutting stock problem* from the homework.
- The large rolls from which the smaller rools are cut have width W.
- The desired widths of the smaller rolls is represented by vector $w \in \mathbb{R}^m$.
- In this problem, potential columns correspond to feasible patterns.
- A given column vector a corresponds to a feasible pattern if and only if

$$\sum_{i=1}^{m} a_i w_i \leq W$$

and a contains only nonnegative integers.

The Column Generation Subproblem

- The cost of every pattern (column) is identical.
- Hence, the column generation subproblem is

$$
\begin{aligned}
max \ & \sum_{i=1}^{m} p_i a_i \\
s.t. \ & \sum_{i=1}^{m} w_i a_i \leq W \\
& a_i \geq 0 \\
& a_i \quad integer
\end{aligned}
$$

- This problem is known as the *integer knapsack problem*.
- Think of a shopping spree in which you try to maximize the value of the set of items that will fit into a shopping cart.
- This problem can be solved using *dynamic programming*.

Finding an Initial BFS

- For this problem, an initial BFS is easy to find.
- Take the i^{th} basic column to be the i^{th} unit vector, i.e., the pattern obtained by cutting one roll of width w_i.
- This set of columns forms an initial feasible basis.
- Of course, these columns are not likely to be used in an optimal solution.

Algorithm Summary

- Construct the initial BFS and add these columns to the set I.
- Solve the restricted LP and calculate the optimal dual solution.
- Solve the column generation subproblem (CGS).
- If the optimal solution to the CGS has negative cost, then add the new column to I and iterate.
- Otherwise, the current solution is optimal.

Constraint Generation Methods

- We can use the same methodology to solve problems with large numbers of constraints.
- Again, recall that we only really "need" the constraints that are binding at optimality.
- Actually, we only need the constraints whose corresponding dual variable has nonzero value at optimality.
- Keeping unneeded constraints in the formulation causes the size of the basis to increase.
- The size of the basis is one of the biggest determinants of the speed of the simplex algorithm.

Development of the Method

- We wish to solve an LP with a large number of rows.
- The method is the same as for column generation, except that now we solve the problem on a restricted row set.
- We attempt to generate an inequality from the global set that is *violated* by the current optimal solution.
- This is called the *separation problem* because it is the problem of separating the current solution from the polyhedron with a hyperplane.
- Note that in the dual, this method is a column generation method, so we have already developed all the machinery we need.

Generic Constraint Generation Algorithm

- Consider the *restricted problem* obtained by considering only the subset of the rows indexed by set I.

$$\begin{aligned} &min\ c^T x \\ &s.t.\ \ a_i^T x \geq b \quad \forall i \in I \end{aligned}$$

- Solve this LP and calculate the optimal primal solution $\hat{x}$.
- Now, we must generate a new row a_j for which $b_j - a_j\hat{x} < 0$.
- This can be done by solving the *constraint generation subproblem*

$$\min_{a \in R} c_a - a^T x,$$

where R is the global set of constraints.

- Add the new constraint to the set I and re-solve.

Maintaining the Restricted Problem

- Again, many variants of this algorithm can be obtained by changing how the set I is maintained.
- One obvious variant is to simply maintain every constraint that has been generated so far in I.
- Another variant is to throw away all the nonbinding constraints after each iteration.
- There are many intermediate options.