

# Algorithms in Systems Engineering

## ISE 172

### Lecture 21

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## References for Today's Lecture

- Required reading
  - CLRS [Chapter 23](#)
- References
  - R. Sedgwick, *Algorithms in C++* (Third Edition), 1998.

## Spanning Trees

- Given a connected undirected graph  $G = (V, E)$ , a *spanning tree*  $T$  of  $G$  is a subgraph that is a tree and whose vertex set is all of  $V$ .
- Since the vertex set of any such spanning tree is  $V$ , we will sometimes equate the edge set of a spanning tree with the spanning tree itself.
- Every *minimal* connected subgraph is a spanning tree (and vice versa).
- In other words, a subgraph is a spanning tree if and only if it is connected and removing any edge will disconnect it.
- If we are looking for the most inexpensive set of links that connect a set of geographically dispersed points, we want a spanning tree.
- Spanning trees arise frequently in applications, especially those with a *network design* component.
- They also arise in other applications, such as the design of integrated circuits.

## Minimum Weight Spanning Trees

- Consider an undirected graph  $G = (V, E)$  with weight vector  $w \in \mathbb{R}^E$ .
- If  $T \subseteq E$  is a spanning tree of  $G$ , the *weight* of  $T$  is

$$\sum_{e \in T} w_e$$

- The *minimum weight spanning tree* (MST) problem is that of finding, among all spanning trees of  $G$ , one that has minimum weight.
- How many spanning tree are there?
- What about simply enumerating all of them?

## Finding a Minimum Weight Spanning Tree

- Although finding an **MST** may seem to be a difficult problem, it can be solved efficiently.
- The first algorithm we'll consider uses another variant of graph search to build a search tree that is guaranteed to be an **MST**.
- We build the tree up, adding one vertex at a time.
- At each iteration, we have a partially completed tree that spans the vertices that have been processed so far.
- The vertex that is processed next is the one that is “closest” to the partially completed tree.
- The algorithm is almost identical to **Dijkstra's Algorithm**.

## Algorithm Summary: Prim's Algorithm

- We are given a connected undirected weighted graph  $G = (V, E)$  and we want to find an **MST** of  $G$ .
- **Prim's Algorithm**
  - Arbitrarily choose a source node  $r$ .
  - Initialize by assigning  $d(r) = 0$  for the source node and  $d(v) = \infty$  for all other nodes  $v \in V \setminus \{r\}$ .
  - Place  $r$  on the list  $L$  of unprocessed nodes.
  - While  $L$  is not empty
    - \* Choose  $v \in L$  such that  $d(v) = \min_{u \in L} d(u)$ .
    - \* For each neighbor  $x$  of  $v$ , set  $d(x) = \min\{d(x), w_{\{v,x\}}\}$ .
- When we're finished, the search tree will be an **MST**.
- Why is this algorithm correct?
- How do we implement it?
- What is the running time?

## Another View of Prim's Algorithm

- Prim's Algorithm can be viewed as a special case of graph search.
- The algorithm can also be viewed as a special case of another general class of algorithms called *greedy algorithms*.
- A *greedy algorithm* is one that makes the choice at each step that looks the best “at the moment” and doesn't reconsider that choice later.
- We can view the construction of an MST as a greedy algorithm, but first we must define some terminology.
- Given an undirected graph  $G = (V, E)$ , a *cut* is a set  $S \subset V$  that defines a partition of  $V$  into two nonempty subsets,  $S$  and  $V \setminus S$ .
- An edge is said to *cross the cut* if it connects a node in  $S$  to a node in  $V \setminus S$ .
- Our goal is to build a spanning tree by adding one edge at a time to a set  $T$  in a “greedy” fashion.
- Basically, we just need to somehow guarantee ourselves that at each step, the current set can be “extended” to an MST.
- How do we do that?

## Safe Edges

- Let's assume that our current set of edges  $T$  already satisfies the property that  $T$  can be extended to an **MST**.
- Question: What edges can we add to  $T$  to maintain the property?
- Answer: Any edge that is a minimum edge crossing some cut  $S$ .
- Rationale: In any connected graph, there must be an edge crossing each cut in the graph (**why?**)
- We will call such edge a **safe edge** if it also doesn't create a cycle when added to  $T$ .
- How do we find such an edge?
  - **Prim's Algorithm** simply considers the cut  $S$  consisting of nodes that have already been processed.
  - At each step, we add the minimum edge crossing that cut.
  - There are other possibilities, however.



## Generic Greedy Algorithm for Building an MST

- Generic greedy algorithm for constructing a spanning tree.
  - Set  $T = \emptyset$ .
  - Select a **safe edge** and add it to  $T$ .
  - Repeat until  $T$  is a spanning tree.
- This is guaranteed to work, no matter how the safe edges are selected.